



# NGRM700

Neutral grounding resistor monitor



## Intended use

The NGRM700 is only intended for use in high-resistance grounded systems. In these systems, the NGRM700 monitors

- the current through the neutral-grounding resistor (NGR),
- the voltage between the star point of the transformer and earth (voltage drop across the NGR),
- the condition of the NGR,
- line-to-line and line-to-earth voltages.

This quick-start guide does not replace the operating manual of the device.

Download: [www.bender.de/manuals](http://www.bender.de/manuals)

## Safety instructions



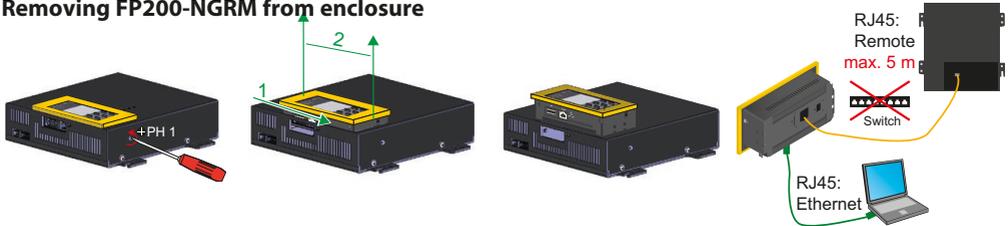
### **DANGER** of electrocution due to electric shock!

Touching live parts of the system carries the risk of:

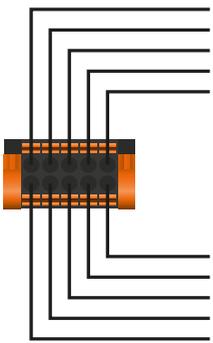
- An electric shock
- Damage to the electrical installation
- Destruction of the device

**Before installing** and connecting the device, make sure that the **installation has been de-energised**. Observe the rules for working on electrical installations.

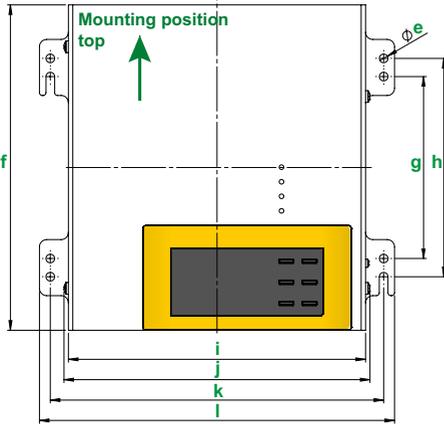
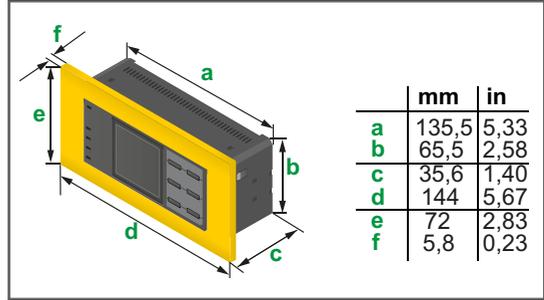
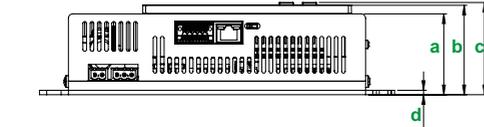
## Removing FP200-NGRM from enclosure



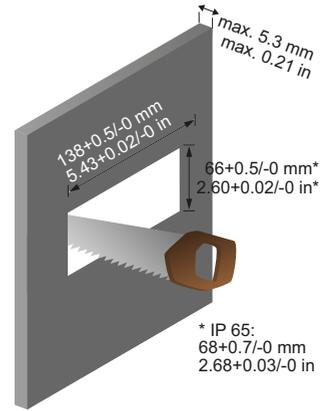
## Connection to the X1 interface

	I1	Pulser IN	
	I2	Reset IN	
	I3	Test IN	
	A	Modbus RTU (A)	
	B	Modbus RTU (B)	
	⊥	Ground	
	M+	Analogue output	
	Q2	Open Collector: Pulser OUT	
	Q1	Open Collector: Device health	
	+	Output for supply of external relays (+24 V, max. 100 mA)	

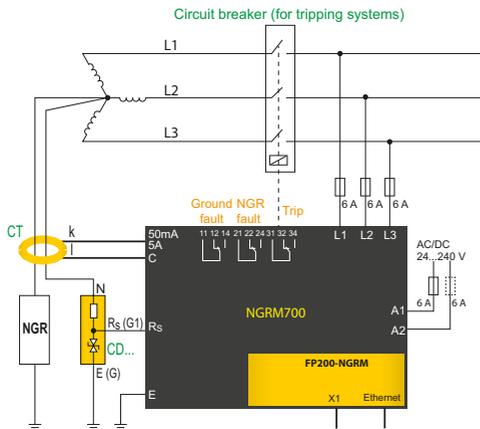
## Dimension diagram NGRM700 and FP200-NGRM



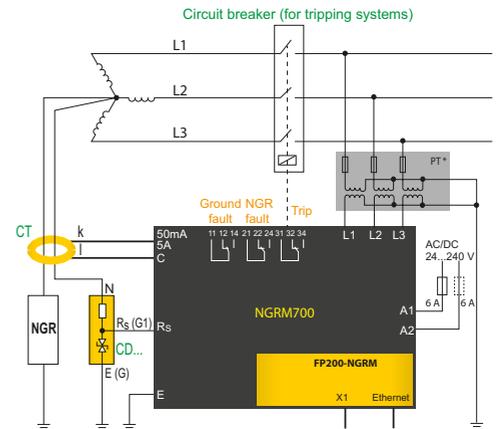
	mm	in
a	55.50	2.19
b	61.40	2.42
c	63.35	2.49
d	3	0.12
e	6	0.236
f	223.50	8.80
g	125	4.92
h	150	5.91
i	205	8.07
j	211	8.31
k	230	9.06
l	245	9.65



## Connection ≤ 690 V



## Connection &gt; 690 V

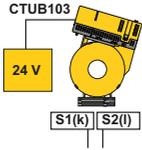
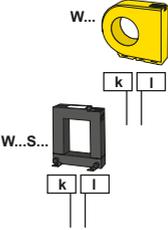
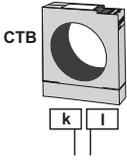


The "N" connection of the CD-series coupling device should be as close to the transformer star point as possible.

\* PT ratio can be selected on the NGRM700

## Measuring current transformer selection

Depending on the system to be monitored, a suitable measuring current transformer is required. All common measuring current transformers (50 mA or 5 A on the secondary side) can be used. The following table helps with the choice:

System type	AC + DC	AC	AC
$I_{NGR}$	1...25 A	5...25 A	5...100 A
Frequency response range	0...3800 Hz	42...3800 Hz	50/60 Hz
Bender CT Ratio	600:1	600:1	60:5
Connecting cable	max. 30 m	max. 40 m	max. 25 m (4 mm <sup>2</sup> /AWG12) max. 40 m (6 mm <sup>2</sup> /AWG 10)
	provided cable or cable of 0.75...1.5 mm <sup>2</sup> /AWG18...16		
$I_{\Delta n}$  (Currents detected)	 AC, pulsed AC, DC	 AC, pulsed AC	 AC, pulsed AC
Type Bender CT	CTUB103  	W20...120 W1-S35...W5-S210  	CTB31...41  
CT: Terminal k	NGRM700: <b>50 mA</b>	NGRM700: <b>50 mA</b>	NGRM700: <b>5 A</b>
CT: Terminal l	NGRM700: <b>C</b>	NGRM700: <b>C</b>	NGRM700: <b>C</b>

**Menu structure**

**1. Data meas. values**

$R_{NGR}$ ,  $R_{NGR}$  rel, Method,  $R_{sense}$ ,  $I_{rms}$ ,  $I_{rms}$  rel,  $U_{rms}$ ,  $U_{rms}$  rel,  $I_{fund}$ ,  
 $I_{fund}$  rel,  $U_{fund}$ ,  $U_{fund}$  rel,  $I_{harm}$ ,  $I_{harm}$  rel,  $U_{harm}$ ,  $U_{harm}$  rel,  $U_{L1L2}$ ,  $U_{L2L3}$ ,  
 $U_{L3L1}$ ,  $f$ ,  $U_{1-E}$  rms,  $U_{2-E}$  rms,  $U_{3-E}$  rms, T

**2. Harmonics**



**3. History**

History, Delete

**4. Pulser**

Pulser,  $t_{Impuls}$

**5. Display**

$R_{NGR}$ ,  $I_{NGR}$

**6. HRG settings**

HRG system	$U_{sys}$ (L-L), $f$ , $I_{NGR}$ nom, $R_{NGR}$ nom
CT	CT primary, CT secondary, CT connection
NGR	Method, PT primary, PT secondary
Phase monitor	Phase monitor, PT primary, PT secondary
Response values	$U_{NGR}$ Trip, $I_{NGR}$ Trip, $>R_{NGR}$ , $<R_{NGR}$ , $t_{NGR}$ trip, GF trip, tGF trip, Alarm stored, $t_{restart}$ , Max. no. of restarts, Trip signal, Upper limit harmonics, Lower limit harmonics
System settings	Earth fault relay ..... Mode, Relay test NGR relay ..... Mode, Relay test Trip relay ..... Mode, Relay test Analogue ..... Mode, Function Digital in/out ..... Device OUT, Pulser OUT, Pulser IN, Reset IN, Test IN Buzzer ..... Buzzer alarm, Buzzer test
Field calibration	

**7. Device settings**

Language, Clock, Interface, Display, Password, Factory setting, Software, Service

**8. Commissioning**

Setting Language, Clock,  $U_{sys}$  L-L,  $f$ ,  $I_{NGR}$  nom,  $R_{NGR}$  nom,  $CT_{primary}$ ,  $CT_{secondary}$ ,  $CT_{Connection}$ , Field calibration

**9. Info**

Device information, Software information, Clock and date information, Ethernet information

**10. Alarm**

Acknowledge, Reset, Test

**Recommended minimum value  $R_{NGR}$  (tripping level 50 %)**

 Temperature range  $-40\dots+70\text{ }^{\circ}\text{C}$ , field calibration at  $25\text{ }^{\circ}\text{C}$ 

 (Values shown in brackets: Limited temperature range  $0\dots+40\text{ }^{\circ}\text{C}$ , field calibration at  $25\text{ }^{\circ}\text{C}$ )

	CD1000/CD1000-2			CD1000-2	CD5000		CD14400					CD25000
$U_{\text{sys}}$	400 V	600 V	690 V	1000 V	2400 V	4200 V	6000 V	6600 V	7200 V	11000 V	14400 V	25000 V
$I_{\text{NGR}}$												
1 A	231 $\Omega$	346 $\Omega$	398 $\Omega$	577 $\Omega$	1386 $\Omega$	—	—	—	—	—	—	—
5 A	46 $\Omega$	69 $\Omega$	80 $\Omega$	115 $\Omega$	277 $\Omega$	485 $\Omega$	693 $\Omega$	762 $\Omega$	831 $\Omega$	1270 $\Omega$	1663 $\Omega$	—
10 A	(23 $\Omega$ )	35 $\Omega$	40 $\Omega$	58 $\Omega$	139 $\Omega$	242 $\Omega$	346 $\Omega$	381 $\Omega$	416 $\Omega$	635 $\Omega$	831 $\Omega$	1443 $\Omega$
15 A	(15 $\Omega$ )	(23 $\Omega$ )	(27 $\Omega$ )	38 $\Omega$	92 $\Omega$	162 $\Omega$	231 $\Omega$	254 $\Omega$	277 $\Omega$	423 $\Omega$	554 $\Omega$	962 $\Omega$
20 A	—	(17 $\Omega$ )	(20 $\Omega$ )	29 $\Omega$	69 $\Omega$	121 $\Omega$	(173 $\Omega$ )	191 $\Omega$	208 $\Omega$	318 $\Omega$	416 $\Omega$	722 $\Omega$
25 A	—	—	(16 $\Omega$ )	(23 $\Omega$ )	55 $\Omega$	97 $\Omega$	(139 $\Omega$ )	(152 $\Omega$ )	(166 $\Omega$ )	254 $\Omega$	333 $\Omega$	577 $\Omega$
30 A	—	—	—	(19 $\Omega$ )	(46 $\Omega$ )	81 $\Omega$	(115 $\Omega$ )	(127 $\Omega$ )	(139 $\Omega$ )	212 $\Omega$	277 $\Omega$	481 $\Omega$
40 A	—	—	—	—	(35 $\Omega$ )	61 $\Omega$	(87 $\Omega$ )	(95 $\Omega$ )	(104 $\Omega$ )	(159 $\Omega$ )	208 $\Omega$	361 $\Omega$
50 A	—	—	—	—	(28 $\Omega$ )	(48 $\Omega$ )	—	(76 $\Omega$ )	(83 $\Omega$ )	(127 $\Omega$ )	(166 $\Omega$ )	289 $\Omega$
100 A	—	—	—	—	—	(24 $\Omega$ )	—	—	—	—	(83 $\Omega$ )	(144 $\Omega$ )

**Maximum trip times  $t(\text{GFtrip})$  for the used CD-NGRM**

The setting for  $t_{\text{GF trip}}$  must not be longer than the maximum operating time of the CD series... coupling device. The table shows an overview of the  $t(\text{GFtrip})$  settings for the coupling device used:

$U_{\text{sys}}$	Coupling device	Ground-fault trip settings (menu 6.5.6) (Select Off for ground-fault alarm-only systems)	max. tGF trip (menu 6.5.7) (For ground-fault tripping systems)
400... 690 V	CD1000	on or off	24 h
	CD1000-2		
691... 1000 V	CD1000	on	300 s
	CD1000-2	on or off	24 h
	CD5000		
1001... 4300 V	CD5000	on or off	24 h
4301... 14550 V	CD14400	on	60 s
	CD25000		
14551... 25000 V	CD25000	on	10 s

## Initial commissioning

The commissioning wizard (**menu 8**) queries the following parameters

(additional settings: menu 6):

Language (8.2)	Select	RNGR nom (8.8)	
Date (8.3)	Set	CT primary (8.9)	
Time (8.4)	Set	CT secondary (8.10)	
Usys L-L (8.5)	System voltage	CT connection (8.11)	50 mA or 5 A
Frequency (8.6)	50 or 60 Hz	Field calibration (8.12)	
INGR nom (8.7)			Start or do not start

### 1. Setting the response values (menu 6.5)

- Trip threshold for voltage ( $U_{NGR}$ )
- Trip threshold for current ( $I_{NGR}$ )
- Trip threshold for resistance ( $R_{NGR}$ )

**i** *Low trip threshold values: may lead to false tripping.  
High trip threshold values: the device may not trip.*

### 2. System settings of the relay -output modes (menu 6.6)

The factory setting for the relay outputs is fail-safe. The relays only change state when a test is initiated if so configured.

**i** **Fail-safe:** *The relay is energised during normal operation and is de-energised in the event of a fault ("fail-safe").*

**Non-fail-safe:** *The relay is de-energised in normal operation and is energised in the event of a fault ("non-fail-safe").*

### 3. Field calibration (menu 6.7)

After the parameters have been entered, a field calibration can be carried out to set  $R_{NGR} = R_{NGR\ nom}$ . For the field calibration the device must run in auto mode (menu 6.3.1 = auto)

### 4. Trip signal RMS, fundamental frequency, harmonics

The frequency response for neutral current and voltage trips or alarms can be selected via the "Trip signal" parameter (menu 6.4.11). Trip signal can be:

- **RMS:** The r.m.s. value of  $I$  or  $U$  over the entire frequency range (up to approx. 3.8 kHz).
- **Fundamental frequency:** The r.m.s. value of the fundamental frequency component (50 or 60 Hz) of  $I$  or  $U$ .
- **Harmonics:** The filtered r.m.s. value of the selected frequency range where H0 = DC; H1 = fundamental frequency; H2 = 2 x fundamental frequency (second harmonic); ... H32 = 32 x fundamental frequency (32nd harmonic)

**i** *In the "Harmonics" measured value display (menu 2) all frequencies are always displayed. This is independent of the trip signal setting.*

**i** *On the data measured values display (menu 1), the measured resistance can be shown in  $\Omega$  or % of nominal, and the measured current can be shown in A or % of nominal. (in A or %). The selection is entered in "Display" (menu 5).*

### 5. Initial measurement

During device start, all measured values are recorded.

## Factory settings

Menu 6.1: HRG system		2. PT primary	1	Menu 6.6: System settings	
1. $U_{\text{sys (L-L)}}$	400 V	3. PT secondary	1	1. Ground-fault relay	Mode: Fail-safe
2. CD-NGRM	CD1000	<b>Menu 6.5: Response values</b>			Relay test: on
3. Frequency	50 Hz			1. $U_{\text{NGR Trip}}$	60 %
4. $I_{\text{NGR nom}}$	5 A	2. $I_{\text{NGR Trip}}$	60 %	Relay test: on	
5. $R_{\text{NGR nom}}$	470 $\Omega$	3. $> R_{\text{NGR}}$	150 %	3. Trip relais	Mode: Fail-safe
<b>Menu 6.2: CT</b>		4. $< R_{\text{NGR}}$	50 %		Relay test: on
1. CT primary	600	5. $t_{\text{NGR Trip}}$	0 s	4. Analogue	Mode: 4-20 mA
2. CT secondary	1	6. Ground fault trip	ja		Function: R NGR
3. CT connection	50 mA	7. $t_{\text{GF Trip}}$	5 s	5. Dig. in/out	Device OUT: Fail-safe
<b>Menu 6.3: NGR</b>		8. Alarm stored	on		Pulser OUT: Non-fail-safe
1. Method	auto	9. $t_{\text{restart}}$	5 s		Pulser IN: Active high
2. PT primary	1	10. Restart count	2		RESET IN: Active high
3. PT secondary	1	11. Trip Signal	RMS	TEST IN: Active high	
<b>Menu 6.4: Phase monitor</b>		12. Upper limit harmonic	32	6. Buzzer	Buzzer alarm: off
1. Phase monitor	on	13. Lower limit harmonic	0		Buzzer test: on

## Technical data

Rated voltage.....690 V  
 Overvoltage category .....III  
 Nominal supply voltage  $U_s$   
 $\leq 2000$  m ..... AC/DC, 24...240 V  
 $\leq 2000$  m (for UL applications) ..... AC/DC, 48...240 V  
 $\leq 2000$  m (for AS/NZS 2081 appl.) ..... AC/DC, 48...230 V  
 $> 2000$  ...  $\leq 5000$  m ..... AC/DC, 24...120 V  
 $> 2000$  ...  $\leq 5000$  m (for UL and AS/NZS 2081 appl.) .....  
 ..... AC/DC, 48...120 V  
 Tolerance  $U_s$  .....  $\pm 15$  %  
 Tolerance  $U_s$  (for UL applications) .....  $-50$ ... $+15$  %  
 Tolerance  $U_s$  (for AS/NZS 2081 appl.) .....  $-25$ ... $+20$  %

Frequency range  $U_s$  ..... DC, 40...70 Hz  
 Power consumption (typ. 50/60 Hz) .....  $\leq 6.5$  W / 13 VA  
 Switching elements (Ground-fault, NGR, trip relay)  
 .....Changeover contacts, configurable fail-safe/non-fail-safe  
 Contact data acc. to IEC 60947-5-1  
 Rated operational voltage ..... AC 250 V/250 V  
 Utilisation category ..... AC-13/AC-14  
 Rated operational current AC ..... 5 A/3 A  
 Rated operational current AC (for UL appl.) ..... 3 A/3 A  
 Rated operational current DC ..... 220/110/24 V  
 Utilisation category ..... DC12  
 Rated operational current DC ..... 0.1/0.2/1 A  
 Minimum current ..... 1 mA at AC/DC  $> 10$  V



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